

# imajbox® 3

## TECHNICAL SPECIFICATIONS

### IMAJBOX® 3S

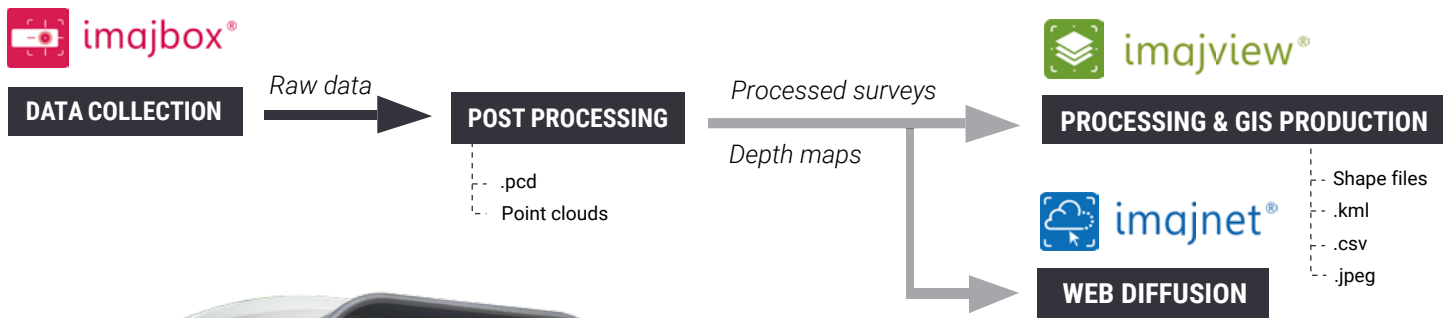
#### FOR GIS ROAD MAPPING

Portable mobile mapping system designed to survey linear infrastructures from any vehicle.

#### A versatile tool

Mounted on cars or trucks, imajbox® can survey from a few to thousands of kilometers.

Punctual, recurrent or nationwide projects, imajbox® is the perfect tool to survey a network, thus having up-to-date data.



#### A response to many issues:

- GIS and mapping
- Infrastructure assessment
- Engineering studies
- Linear Referencing System
- Maintenance management
- Work control
- Planning and budgeting
- Monitoring...



#### ACCURATE

Proprietary algorithms to process sensors' raw data for the continuous and accurate spatial positioning



#### SIMPLE

Independent, all-in-one, standalone and autocalibrated. No wiring required.



#### PRODUCTIVE

High speed survey for large scale data collection.



#### CONNECTED

Controlled by WiFi and connectors for external sensors integration.



#### ADJUSTABLE

Easily mounted in every orientations with the tripod's suction pads.

## GNSS RECEIVER

.... 32 channels for simultaneous tracking of all visible satellites

**GPS:** L1  
**GLONASS:** L1  
**Galileo:** E1  
**SBAS:** EGNOS, WAAS, GAGAN, MSAS

.... **Supported real time modes:**  
 Standalone, SBAS

.... **Supported post processed modes:**  
 dGNSS (GPS+GLONASS)  
 EMS (EGNOS SBAS in post process)

MODE	HORIZONTAL ACCURACY
Standalone	2m
SBAS	1m
dGNSS	0,5m

.... **Time to first fix:**  
 Cold start < 45s  
 Warm start < 20s

## ANTENNA

.... **Integrated**  
 GPS/GLONASS/GALILEO antenna

.... **Connector for external antenna (SMA)**  
 Auto-switch to an external antenna (50ohms load)

.... **Patch antenna for external use:**  
 GPS/GLONASS L1 patch antenna

.... **Interface for lever arm input**

## IMU

**DX3 inertial movement unit 6 axis**

.... **Gyroscopes:**  
 Dynamic range:  $\pm 280^\circ/s$   
 In-run bias stability:  $12^\circ/hr$   
 Angular random walk:  $0,56/\sqrt{hr}$

.... **Accelerometers:**  
 Dynamic range:  $\pm 5g$   
 In-run bias stability:  $0,25mg$   
 Velocity random walk:  $0.073m/sec/\sqrt{hr}$

## IMAGE SENSOR

.... **Sensor**  
 Single CMOS Global Shutter 8,9MP

.... **Resolution**  
 Standard: 4096x2160 pixels

.... **Auto-trigger**  
 Inter distance of image acquisition configurable (from 0,5m to 10m).

.... **Maximum Frame rate**  
 10fps (full resolution)

.... **Ultra-fast auto-exposure**  
 3 zones presets

.... **Optimized debayering**

## OPTICS

.... **Fixed focus multi-lens**

.... **Deep depth of field**  
 Sharp from 0,5 to 100m from camera

.... **HFoV**  
 100°

## STORAGE

.... **Internal SSD**  
 128 GB

.... **Support for real time external storage via USB3**  
 (Pendrive, HDD, SSD)

.... **Data management interface**  
 for copying from internal SSD to USB

.... **Support for Ethernet**  
 SAMBA share for accessing internal SSD directly

## CONNECTIVITY

USB 3

Ethernet

Wi-Fi host (for web remote control)

Wi-Fi client (for corrections)

## SOFTWARE

.... imajbox® is delivered with Post processing software for Windows X64:

imajing browser

imajing 3D Pro

imajing tight hybrid algorithms

## OPERATIONAL LIMITS

.... **Survey speed**  
 0 to 130 km/h

.... **Temperature**  
 -10°C to 40°C

## HARDWARE

.... **Dimensions**  
 Height: 175 mm  
 Length: 165 mm  
 Width: 145 mm

.... **Weight**  
 2 kg

.... **Power supply**  
 12V / 3A  
 Internal battery for 3h standalone survey

.... **Package**  
 1 unit delivered in a small fly case  
 3 suction pads  
 1 USB Pendrive 128GB  
 1 external patch antenna  
 Security strap  
 Cigarette lighter power supply cable  
 AC/DC converter 110/240V 12V 3A